Does your 3 axis servo robot have limitations in additional positions and motions? HYROBOTICS ! RAISING AUTOMATIC MOTIVATION !



NEXIA Series Control Features (More flexibility with simple operation)

- EASY TO ADD POSITION, MOTIONS IN & OUT SIDE OF MOLDING MACHINE
- INSERT MOLDING IS READY (FROM STACKING OR FEEDER SYSTEMS)
- VERTICAL OR HORIZONTAL STACKING IS READY (with Simple Data input)
- USER OUTPUT / INPUTS FOR SECONDARY AUTOMATION ARE READY
- INPUT/OUTPUT SIGNAL VIEW FROM MANUAL AND AUTO. STEP BY STEP TO CREAT NEW MOTION.

intricate molding automation, including insert molding, palletizing, de-gating, and other secondary automation. If you have experienced limitations in motions with your current automation that require special factory programming, HYRobotics has the solution for you. HYRobotics NEXIA Series robots have won the approval of North American molders with high quality components and 3 axis servo featured controls that offer flexibility and ease of operation. Enjoy the benefit of full servo featured NEXIA series Robot !

HYROBOTICS CORP, 5988 MID RIVERS MALL DR. ST.LOUIS MO 63304 Website : www.hyrobots.com, Email : Sales@hyrobots.com

All information is subject to change without any notice , some function required to have additional options.

HYNC-700 TOUCH SCREEN FEATURES AND FUNCTIONS

ENJOY THE BENEFIT OF FULL SERVO FEATURED CONTROL!

If you have experienced limitations in motions with your current automation that require special factory programming, HYRobotics has the solution for you. HYRobotics NEXIA Series robots have won the approval of North American molders with high quality components and 3 axis servo featured controls that offer flexibility and ease of operation.

SrchOrg 2 Mold: W1	♦ SERVO ORIGIN	TkPos 2 Mold: W1	◆ TAKE OUT METHOD	StepSet 2 Mold: W1	♦ STEP SCREEN
Search origin by pressing start.	INITIAL SCREEN FOR FINDING ORIGIN POINT OF SERVO POSI- TIONS. WITH POWER ON, ROBOT WILL SEARCH ORIGIN POINT TO LOCATE SERVO MOTOR'S HOM- ING POSITION WITH THE ORDER OF SAFETY.	Divitime Speed TkTime TkMethod P SucOn ChuckOn PBripOn Close - 105 +	USING SIMPLE ICONS, THE TAKE OUT METHOD IS SE- LECTED DURING MOLD SETUP. SUCTION, CHUCKING OR OTHER ADDITIONAL OUTPUT CAN BE SELECTED. J MOTION SET UP NEED TO BE DONE IN THIS STEP.	N0 S T E P 1 WaitPos 2 TkPos 3 AscPos 4 ReiPos DelStep GripPos Inllait IF Else Uoutput Image: StepFw	POWEFUL STEP SCREEN CAN ALLOW ADD POSITION, MOTION OR DELETE STEP AND COMMUNICATING WITH SECONDARY AUTOMATION. THIS STEP SCREEN WILL BE USED TO EDIT OR ADD STEPS TO THE CURRENT OR NEW MOLD FILE. USER INPUT OR OUTPUT CAN BE ADDED IN THIS STEP EDIT SCREEN.
Main 12 Mold: REZZO1 Set Maintenance Maintenance RictPos SampiPos EOATPos T/S Aiarmin Systime Utual Erhist Systiff RetOrg Manual MoldData Auto	◆ MAIN SCREEN THIS IS MAIN SCREEN HAS MAN- UAL, MOLD MANAGER (STEP CREATION), AUTO SCREEN. EASY ROBOT MANAGEMENT SCREEN HAS ALL FUCTION IN- CLUDING SETTING REJECT POSI- TION, THIS WILL ALLOW ROBOT SEPARATE THE REJECTED PARTS AND ALSO J MOTION SETTING OR ALARM, SYSTEM TIMES.	Natifies 2 Mold: With Uptime Seeed Ourrent Nemory Pride 0.00 Pride P	◆ POSITION SETUP POSITIONS ARE ENTERED BY TEACHING ROBOT, USING JOG BUTTONS. LOCATE ROBOT AND SAVE POSITION. THIS ALSO CAN CREAT ADDITIONAL STEP DUR- ING ANY STEPS WITH ADD POSI- TION FUNCTION. SPEED AND DELAY TIME WILL BE SAVED SEPARATELY FOR THIS STEP. CURRENT AND MEMO- RIZED POSITION ARE SHOWN IN THE SCREEN.	GripPos 2 Mold: W1 DlyTime Speed GripDly 0 Sec 0	◆ NUMERIC INPUT NUMERIC DATA IS ENTERED VIA TOUCH SCREEN FOR DELAY TIMER AND SPEED, POSITION CONTROL DURING AUTO MODE.
NoldData 2 Wold: W1 No Nold 1 COCK 2 W1 3 CUP 4 ANYCALL 5 CASE1 6 WATIZ Image: Set of the set	◆ MOLD MANAGEMENT MOLD PROGRAMS CAN BE MADE , OPENED, SAVED, RESTORED, COPIED, EDITED EASILY. UP TO 99 MOLD NAME CAN BE SAVED IN THE SYSTEM, EACH MOLD CAN HAVE UP TO 20 MOTION STEPS. POWERFUL STEP SETTING ALLOW TO CREAT STEP FOR POSITION AND MOTION.	Detail 2 Vold: W1 Fiber AscDsc Fiber AscDsc Times - Speed TrvsDis FwBwDis AscHeight Post Pos2 Pos3 Pos4 CLEAR Releaser Releaser Release2	◆ PALLETIZING SETUP SCREEN FOR PALLETIZ- ING AND STACKING OF PROD- UCT. NEXIA ROBOT CAN STACK HORIZONTALLY, VERTICALLY ALSO SEPARATE CAVITY WITH ADDITIONAL VACUUM OR CHUCKING CIRCUIT. OUTPUT AND INPUT COMMUNICATION REQUIRED FOR OPERATION.	No Moid Provide Provid Provide Provide	• DATA INPUT ALPHA NUMERIC DATA IS ENTERED VIA TOUCH SCREEN FOR MOLD NAME OR STEP INFORMATION.
Korusi 2 Kord: NI IN OUT INT Image: Core of the c	◆ MANUAL MODE VACUUM, CHUCKING, GRIP, NIPPER CAN BE MANUALLY OPER- ATED. IN / OUT / INTERLOCK SIGNAL CAN BE MORNITORED WITH THIS SCREEN. DETAIL ON EACH I/O AVAILABLE ON SUB SCREENS. 3 AXIS SERVO OPERA- TION WITH JOG BUTTON WITH SPEED ADJUSMENT FUNCTION.	Dotail 2 Mold: W1 Pitch - Times - OlyTime Speed TrvSI FWBW/Is Ascheight Spout Spout3 Spout4 CLEAF Close	◆ INSERT GRIP SETUP SCREEN FOR PALLETIZED INSERT LOADING. NEXIA ROBOT GRIPS INSERT FROM FEEDER OR STACKED INSERT WITH THE INPUT OF NUMBER OF EACH AXIS. COMMU- NICATION OF I.O WITH SECON- DARY AUTOMATION REQUIRECD.	Auto 2 Vold: W1 Target: 1 0 0 0 0 Cyrcet: 1 5 0 0 CYCLE: 1 5 0 CYCLE: 1 5 0 CYCLE: 3 5 0 CYCLE	◆ AUTO SCREEN TARGET COUNT, CURRENT COUNT, CYCLE TIME, TAKE OUT TIME, UNLOAD PALLET- IZING, INSERT LOAD DE- PALLETIZING, MOTION SPEED, DELAY TIME, POSITION ADJUSTMENT OF EACH STEP. IT HAS PAUSE , RE-START FUNCTION.

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